

Part II Astrophysics/Physics

# Astrophysical Fluid Dynamics

## Lecture 1 : Introduction

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# Administrative details

- Course materials accessible via moodle:
  - 24 lectures (recordings)
  - Slide sets for each lecture
  - PDF notes – companion to the lectures (not intended to be complete)
  - Four examples sheets
- Books:
  - Course closely follows “Principles of Astrophysical Fluid Dynamics” by C.J.Clarke and R.F.Carswell
  - Other good reference books:
    - “Fluid Mechanics” (2<sup>nd</sup> Ed.) by L.D.Landau & E.M.Lifshitz
    - “The Physics of Fluids & Plasmas: An Introduction for Astrophysicists” by A.Rai Choudhuri

# Today's Lecture

- A : Basic Principles
  - What is a fluid?
  - Where do we find fluids in astrophysics?
  - Concept of a fluid element
  - Collisional and collisionless fluids
- B : Formulation of the Fluid Equations (Part I)
  - Eulerian vs Lagrangian frameworks
  - Descriptions of the kinematics (streamlines, particle paths & streaklines)

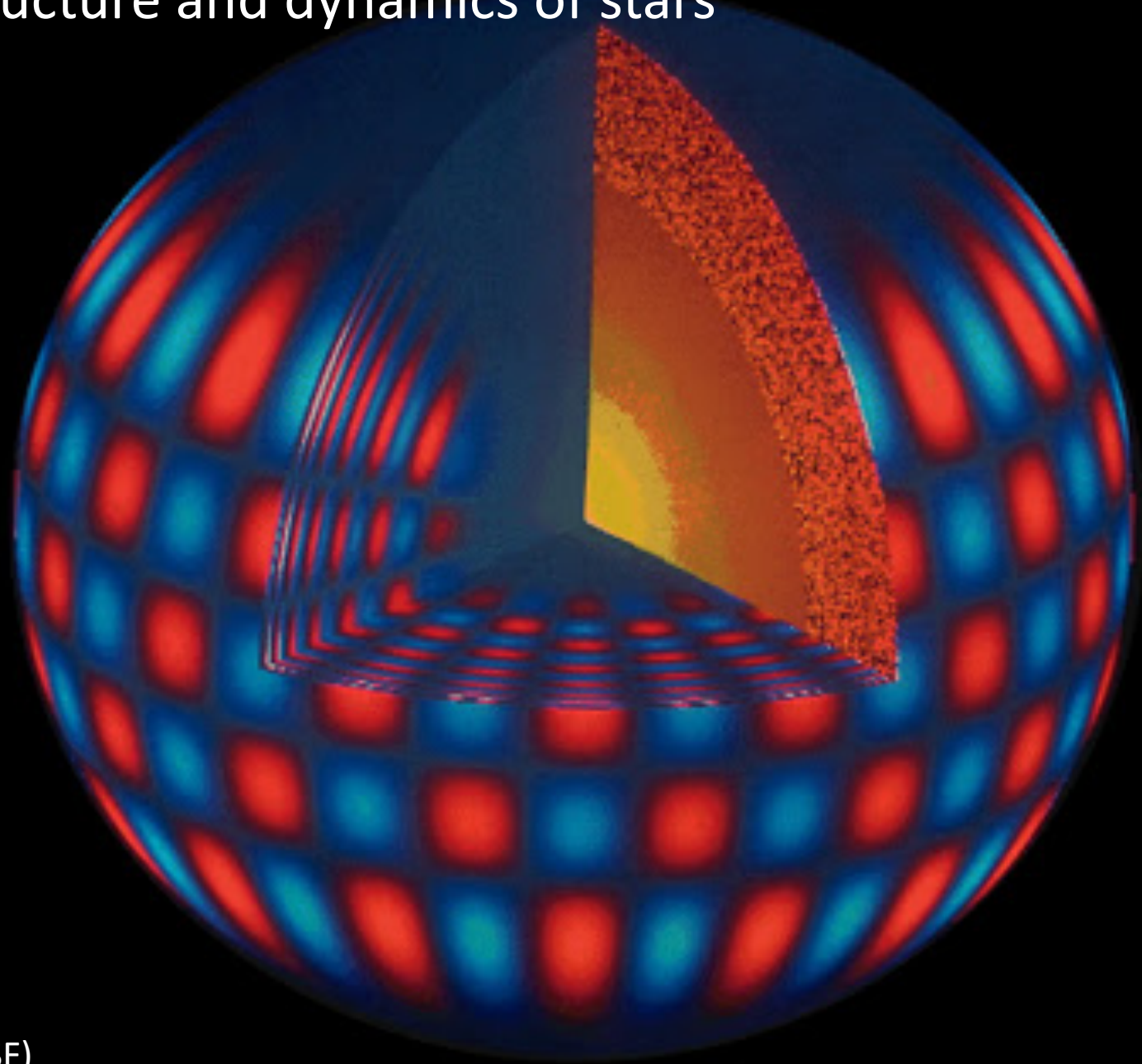
# Chapter A

## Basic Principles

# A : Introduction

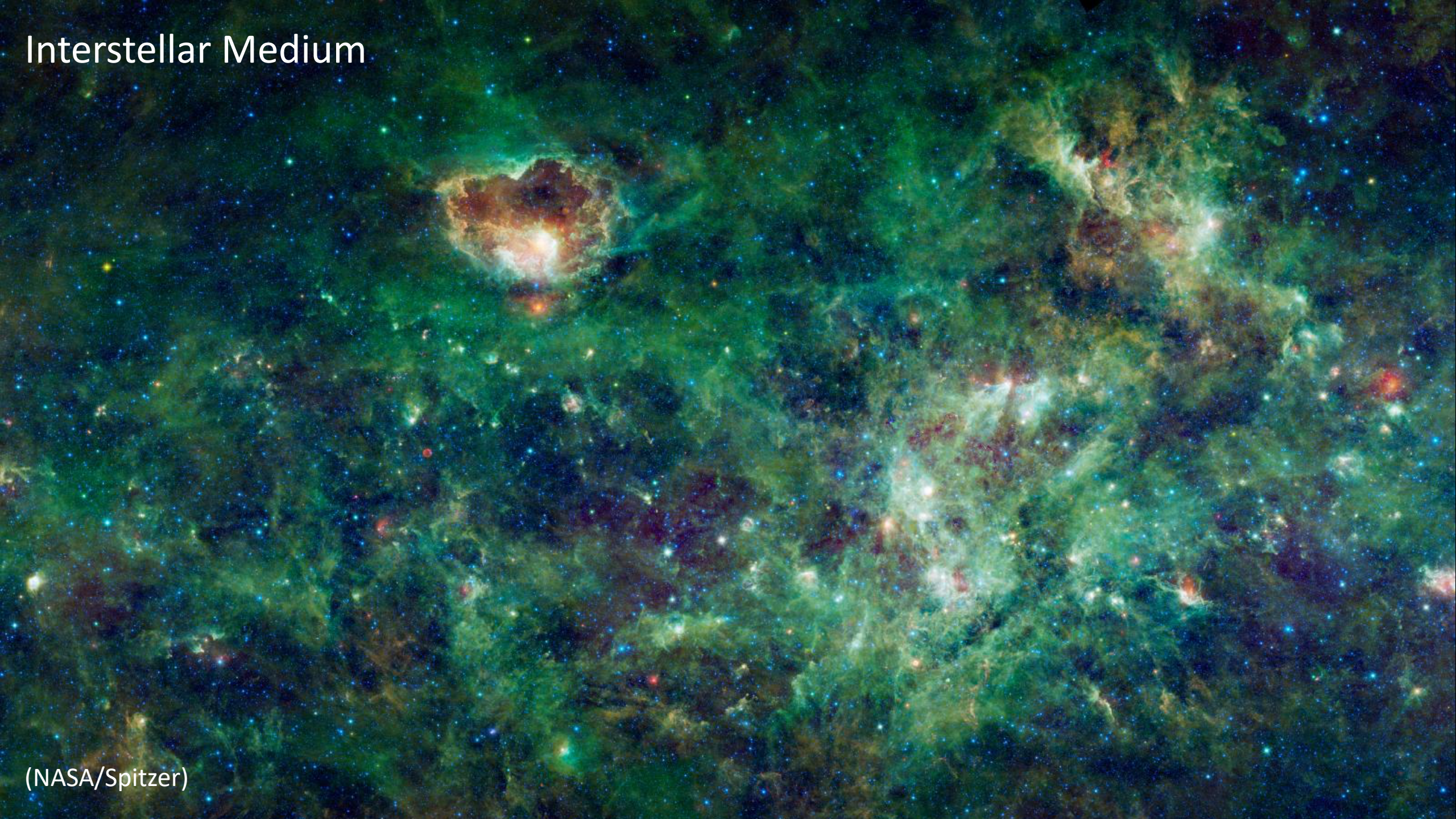
- Fluid flows!
- Fluid is described as continuous medium
  - Possesses well-defined macroscopic properties (density, velocity, pressure, ...)
  - Can approach fluid dynamics from a kinetic theory perspective
  
- Where do we find fluids in astrophysics?

# Internal structure and dynamics of stars



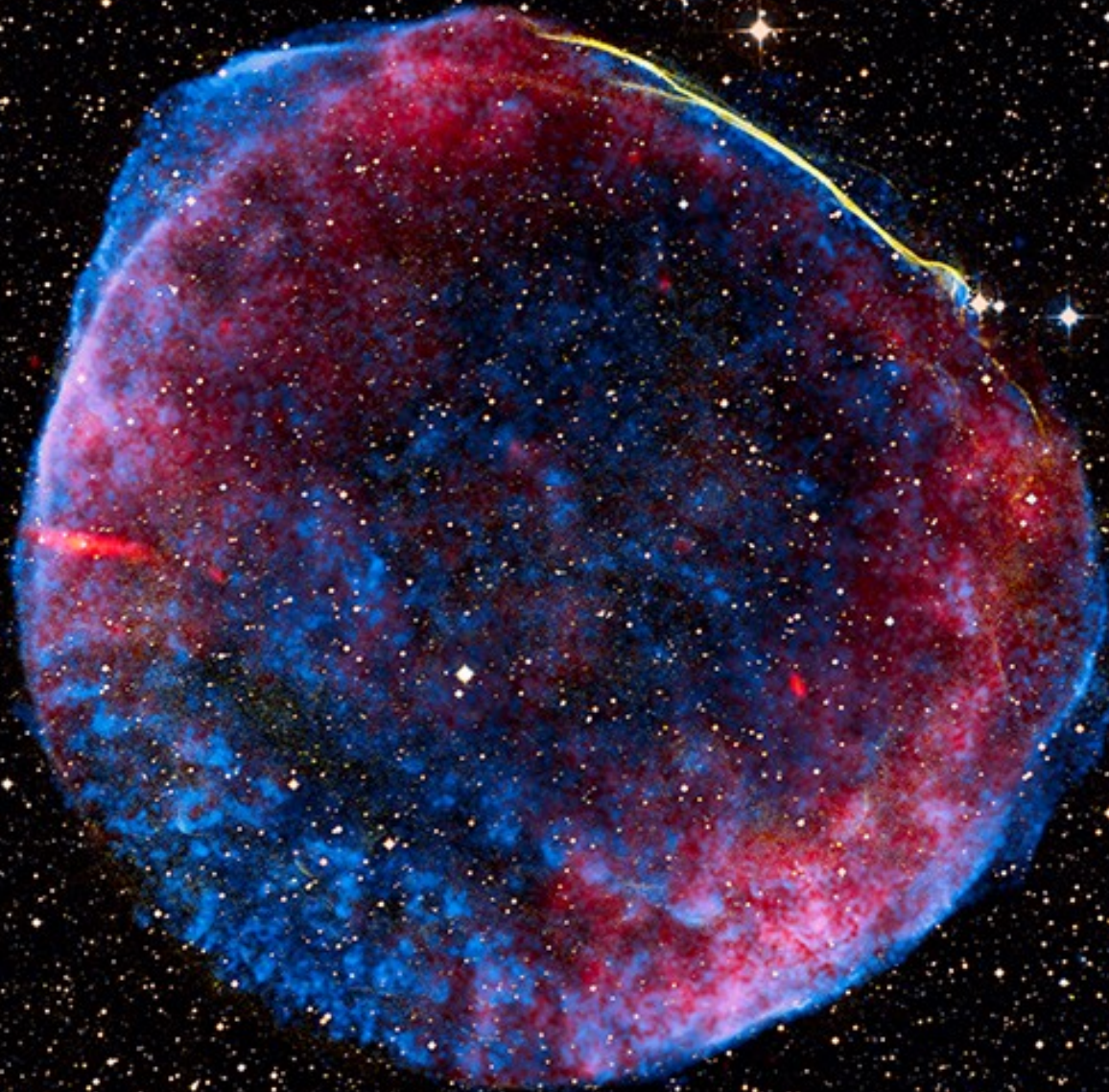
(GONG/AURA/NSF)

# Interstellar Medium



(NASA/Spitzer)

# Supernova Remnants (SN1006)



(NASA/ESA/STScI)

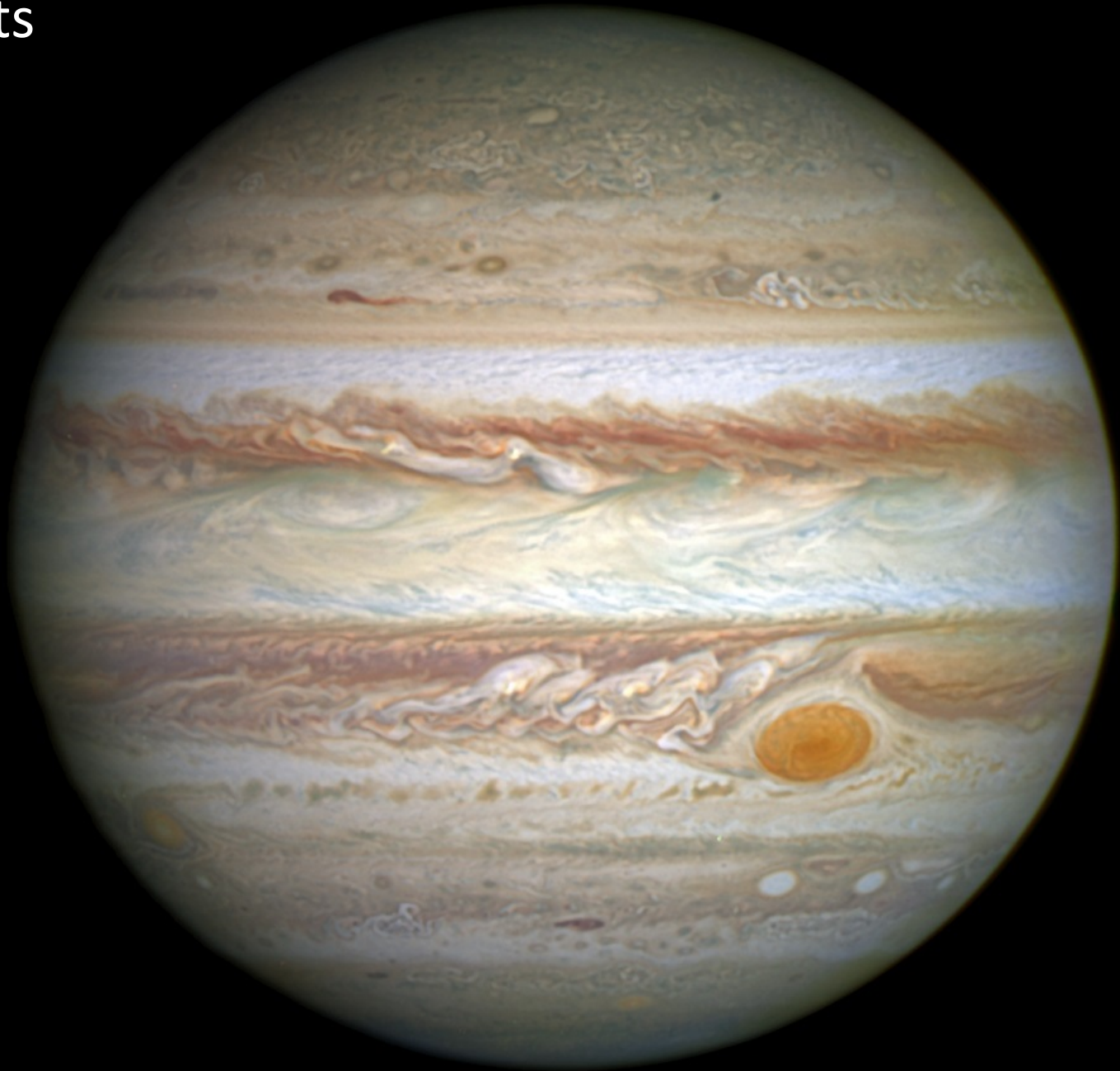


# Accretion disks



(NASA/JPL)

# Giant planets



(NASA/JPL)

**Fluid element** : a region of fluid (size  $l_{\text{region}}$ ) that is

- Small enough that every macroscopic property  $q$  is approx constant

$$l_{\text{region}} \ll l_{\text{scale}} \sim \frac{q}{|\nabla q|}$$

- Large enough to contain large numbers of particles

$$nl_{\text{region}}^3 \gg 1$$

( $n$  is number of particles per unit volume)

If such fluid elements can be defined, continuum description is valid.  
Otherwise, must describe the system at the particle-level.

## A.2 : Collisional vs collisionless fluids

**Mean-free-path  $\lambda$**  : typical distance travelled by a particle before its direction of travel is significantly changed due to particle collisions.

In a **collisional fluid**, we have  $\ell_{\text{scale}} \gg \lambda$ . Then...

- Particles locally attain velocity distribution that maximizes entropy.
- So, well-defined velocity distribution and pressure as function of density  $\rho$  and temperature  $T$

$$p = p(\rho, T)$$

EQUATION OF STATE

- Almost all fluids considered in this course are collisional.

- **In a collisionless fluid**  $\ell_{\text{scale}} \ll \lambda$ . Then
  - Velocity distribution of particles not determined locally
  - Depends on initial conditions and non-local conditions
  - Adds significant complexity to treatment!

## Examples of collisionless fluids

- "Stellar fluid" in a galaxy
- Dark matter
- Intracluster medium of galaxy clusters (transitional case)



Perseus cluster in optical (Chandra; Fabian et al. 2006)



Perseus cluster in X-rays (Chandra; Fabian et al. 2006)

## Intracluster medium : typical properties

- $n_e \sim 0.001 - 0.1 \text{ cm}^{-3}$
- $T \sim 10^7 - 10^8 \text{ K}$  (fully ionized)
- $R \sim 1 \text{ Mpc}$  with  $\sim 100 \text{ kpc}$  core (1pc=3.26 light years)
- Particle-particle collisions due to Coulomb interactions

$$\lambda_e = \frac{3^{3/2} (k_B T_e)^2 \epsilon_0^2}{4\pi^{1/2} n_e e^4 \ln \Lambda}$$

$$\lambda_e = \lambda_i \approx 23 \text{ kpc} \left( \frac{T_e}{10^8 \text{ K}} \right)^2 \left( \frac{n_e}{10^{-3} \text{ cm}^{-3}} \right)^{-1}$$



# Chapter B :

## Formulation of the Fluid Equations

# B.1 : Eulerian vs Lagrangian framework

**Eulerian description** : consider the properties of the fluid as a function of time in a frame of reference fixed in space

$$\rho(\mathbf{r}, t), \quad p(\mathbf{r}, t), \quad T(\mathbf{r}, t), \quad \mathbf{v}(\mathbf{r}, t)$$

**Lagrangian description** : consider the properties of a particular fluid element as a function of time.

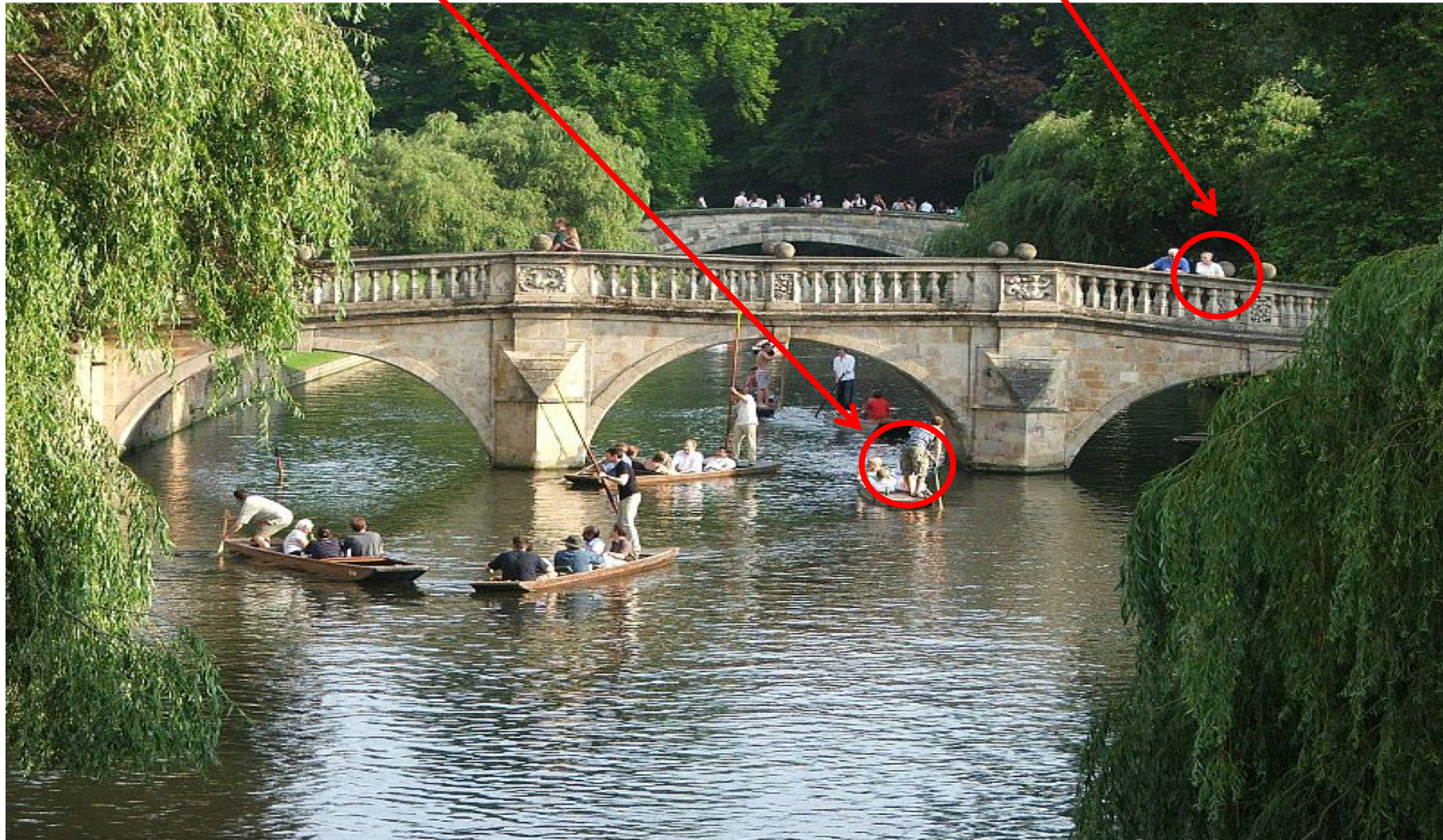
These frameworks underlie the two principle methods of computational fluid dynamics:

- Eulerian → grid-codes (space tiled by a “grid” and fluid flows through that grid)
- Lagrangian → smoothed particle codes (fluid elements treated as “smoothed particles” that propagate through continuous space.

# Formulation of fluid equations

**Lagrangian view**

**Eulerian view**



Consider fluid element with quantity  $Q$ :

- Fluid elements moves from  $\mathbf{r} \rightarrow \mathbf{r} + \delta\mathbf{r}$  in time  $t \rightarrow t + \delta t$
- So, rate of change of  $Q$  for fluid element is

$$\frac{DQ}{Dt} = \lim_{\delta t \rightarrow 0} \left[ \frac{Q(\mathbf{r} + \delta\mathbf{r}, t + \delta t) - Q(\mathbf{r}, t)}{\delta t} \right]$$

- But

$$Q(\mathbf{r} + \delta\mathbf{r}, t + \delta t) = Q(\mathbf{r}, t) + \frac{\partial Q}{\partial t} \delta t + \delta\mathbf{r} \cdot \nabla Q + \mathcal{O}(\delta t^2, |\delta\mathbf{r}|^2, \delta t|\delta\mathbf{r}|)$$

- So

$$\frac{DQ}{Dt} = \lim_{\delta t \rightarrow 0} \left[ \frac{\partial Q}{\partial t} + \frac{\delta\mathbf{r}}{\delta t} \cdot \nabla Q + \mathcal{O}(\delta t, |\delta\mathbf{r}|) \right]$$

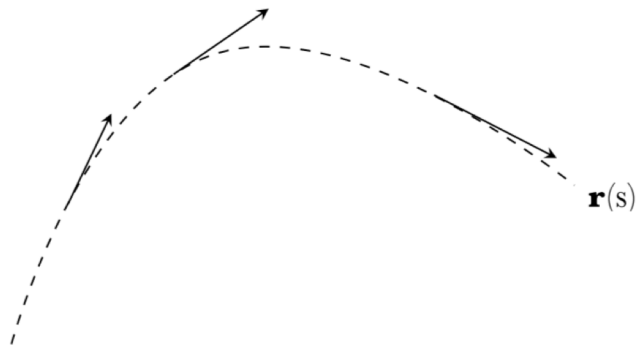
|   |
|---|
| $\underbrace{\frac{DQ}{Dt}}_{\text{Lagrangian time derivative}} = \underbrace{\frac{\partial Q}{\partial t}}_{\text{Eulerian time derivative}} + \underbrace{\mathbf{u} \cdot \nabla Q}_{\text{"convective" derivative}}$ |
|---|

|  |
|--|
| $\mathbf{u} \cdot \nabla \equiv u_x \frac{\partial}{\partial x} + u_y \frac{\partial}{\partial y} + u_z \frac{\partial}{\partial z}$ |
|--|

## B.2 : Kinematics

Definitions:

- **Streamlines** : family of curves that are instantaneously tangent to velocity vector of the flow  $\mathbf{u}(\mathbf{r}, t)$



$$\frac{d\mathbf{r}}{ds} = \left( \frac{dx}{ds}, \frac{dy}{ds}, \frac{dz}{ds} \right)$$

$$\frac{d\mathbf{r}}{ds} \times \mathbf{u} = 0 \quad \Rightarrow \quad \frac{dx}{u_x} = \frac{dy}{u_y} = \frac{dz}{u_z}$$

- **Particle paths** : paths through space taken by individual fluid elements; given by solution of

$$\frac{d\mathbf{r}}{dt} = \mathbf{u}(\mathbf{r}, t)$$

- **Streaklines** : locus of points of all fluid elements that have passed through a given point in the past

$$\mathbf{r}(t) = \mathbf{r}_0$$

(imagine the point as a source of “dye” or “smoke”).

Streamlines, particle paths, and streaklines all coincide if the flow is steady (i.e.  $\frac{\partial \mathbf{u}}{\partial t} = 0$ ).

# Streamlines past an airfoil

